

Algorithmic Game Theory

Summer Term 2026

Exercise Set 4

If you would like to submit your solutions for this problem set, please send them via email to aheuser1@uni-bonn.de by Monday evening. Submitting solutions in groups is also possible.

If you would like to present one of your solutions in class, please use the following link to book a presentation slot by Monday evening:

<https://terminplaner6.dfn.de/b/46b3ae315324d5cf7c5f419a8739c8ec-1735102>

A short meeting to discuss your solution is mandatory before presenting it in class. To book a time slot for this meeting, please use the following link by Monday evening as well:

<https://terminplaner6.dfn.de/b/0f5e8ce957693f056cf215f62c33fbf6-1735091>

Exercise 1:

Consider the following regret-minimization-algorithm.

GREEDY

- Set $p_1^1 = 1$ and $p_j^1 = 0$ for all $j \neq 1$.
- In each round $t = 1, \dots, T$:

Let $L_{min}^t = \min_{i \in N} L_i^t$ for $L_i^t = \sum_{t' < t} \ell_i^{(t')}$ and $S^t = \{i \in N \mid L_i^t = L_{min}^t\}$.
Set $p_i^{t+1} = 1$ for $i = \min S^t$ and $p_j^{t+1} = 0$ otherwise.

You can assume that $\ell_i^{(t)} \in \{0, 1\}$ for all i and t .

- (a) Show that the costs of GREEDY are at most $N \cdot L_{min}^T + (N - 1)$.
- (b) State a scheme for an example such that the stated upper bound of (a) is tight for an infinite number of values T .

Exercise 2:

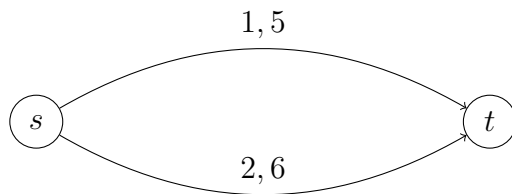
We consider the Multiplicative-Weights Algorithm with a slightly modified update rule. Instead of using $w_i^{(t+1)} = w_i^{(t)} \cdot (1 - \eta)^{\ell_i^{(t)}}$, we now use $w_i^{(t+1)} = w_i^{(t)} \cdot (1 - \eta \cdot \ell_i^{(t)})$. Prove a statement as in Proposition 7.7. for this modified update rule.

Exercise 3:

Referring to the Price of Anarchy from Lecture 8, we introduced a more optimistic point of view called the *Price of Stability* in Lecture 9. For an equilibrium concept **Eq**, it is defined as

$$PoS_{\text{Eq}} = \frac{\min_{p \in \text{Eq}} SC(p)}{\min_{s \in S} SC(s)} .$$

Consider the following symmetric network congestion game with two players:



- (a) What is the Price of Anarchy and the Price of Stability of pure Nash equilibria?
- (b) What is the Price of Anarchy and the Price of Stability of mixed Nash equilibria?

Hint: First of all, determine all mixed Nash equilibria. You might start with a sentence like “Let σ be a mixed Nash equilibrium with $\sigma_1 = (p_1, 1-p_1)$, $\sigma_2 = (p_2, 1-p_2)$ ” and subsequently derive properties of p_1 and p_2 .

Exercise 4:

Consider a (λ, μ) -smooth game with N players and let $s^{(1)}, \dots, s^{(T)}$ be a sequence of states such that the external regret of every player is at most $R^{(T)}$. Moreover, let s^* denote a state that minimizes the social cost. We want to upper bound the average social cost of the sequence of states. To this end, show the following bound

$$\frac{1}{T} \sum_{t=1}^T SC(s^{(t)}) \leq \frac{N \cdot R^{(T)}}{(1-\mu)T} + \frac{\lambda}{1-\mu} SC(s^*).$$

Hint: In this setting, the external regret for player i is the difference between the cost they have incurred and the cost they would have incurred with the best fixed strategy in hindsight.

Exercise 5:

A *fair cost-sharing game* is a congestion game such that for all resources $r \in R$ the delay function can be modeled as $d_r(x) = c_r/x$ for a constant c_r .

Show that fair cost sharing games with n players are $(n, 0)$ -smooth.