

Online Motion Planning, WT 13/14
Exercise sheet 4
University of Bonn, Inst. for Computer Science, Dpt. I

- *You can hand in your written solutions until Tuesday, 19.11., 14:15, in room E.06.*

Exercise 10: Competitive analysis, minimum distance (4 points)

We consider the problem of finding a door in a wall. Starting from point s on a line ℓ , a robot moves along ℓ until it has found a "door" – in other words, a destination point t on ℓ .

It is a common assumption that the target t cannot lie arbitrarily close to s . Recall that ALG is C -competitive, if there exists a constant $\alpha \geq 0$, where

$$ALG(t) \leq C \cdot OPT(t) + \alpha$$

holds for all possible placements of t on ℓ .

Show that the following holds for any two constants $K > k > 0$ and any algorithm ALG for locating t :

ALG is a C -competitive algorithm for finding t , assuming that the distance from t to s is at least k , if and only if ALG is C -competitive assuming that the distance from t to s is at least K .

Please turn the page!

Exercise 11: Competitive complexity (4 points)

Find an upper bound on the competitive complexity of the following strategy *ALG* for locating a door in a wall.

Let $a > 1$ be a constant, then the i -th move ($i = 1, 2, \dots$) of the robot is defined as follows. If i is odd, the robot moves to the point at distance a^{i-1} to the left of its starting point s , otherwise it moves to the point at distance a^{i-1} to the right of s .

Hint: Use the same analysis as used in the lecture for the case $a = 2$.

Exercise 12: Bug leaving from closest vertex (4 points)

We consider a modification to the *BUG* algorithm. The bug starts at its starting point s . In order to reach a destination point t , the bug moves in direction of t , until an obstacle O hinders its movements. As usual, the bug walks along the boundary of O and keeps track of the distance to t .

The modification is as follows. Instead of leaving O at a point closest to t , the bug leaves O at a *vertex* v of O 's boundary which is closest to t . Then, the bug continues in direction of t , until it encounters another obstacle.

Prove or disprove that the modified *BUG* algorithm will eventually reach the target point t , although possibly not as quickly as the unmodified algorithm.